

Computer Assignment 6

beginning on page 128

Chapter 6, section 1, problem 4: Computing a Least-Squares Line

Matlab Input:

```
x = [2.4 3.6 3.6 4.1 4.7 5.3]'  
y = [33.8 34.7 35.5 36.0 37.5 38.1]'  
A = [x, ones(size(x))]  
c = A\y  
t = 2:0.1:9;  
z = polyval(c,t);  
plot(x,y,'x',t,z)
```

Matlab Output:

```
x =  
    2.4000  
    3.6000  
    3.6000  
    4.1000  
    4.7000  
    5.3000  
y =  
   33.8000  
   34.7000  
   35.5000  
   36.0000  
   37.5000  
   38.1000  
A =  
    2.4000    1.0000  
    3.6000    1.0000  
    3.6000    1.0000  
    4.1000    1.0000  
    4.7000    1.0000  
    5.3000    1.0000  
c =  
    1.5826  
   29.6821
```

ABOUT THE MATLAB COMMANDS

ones Create vector or matrix of all ones.

Synopsis (as used): `Y = ones(size(A))`

`Y = ones(size(A))` is the same size as `A` and consists of all 1s.

Synopsis:

`X = A\B` is the solution to the equation $AX = B$

polyval Polynomial evaluation.

Synopsis: `y = polyval(p,S)`

`y = polyval(p,S)`, where `p` is a vector whose elements are the coefficients of a polynomial in descending powers, is the value of the polynomial evaluated at `S`. If `S` is a matrix or vector, the polynomial is evaluated at each of the elements.

plot Linear 2-D plot.

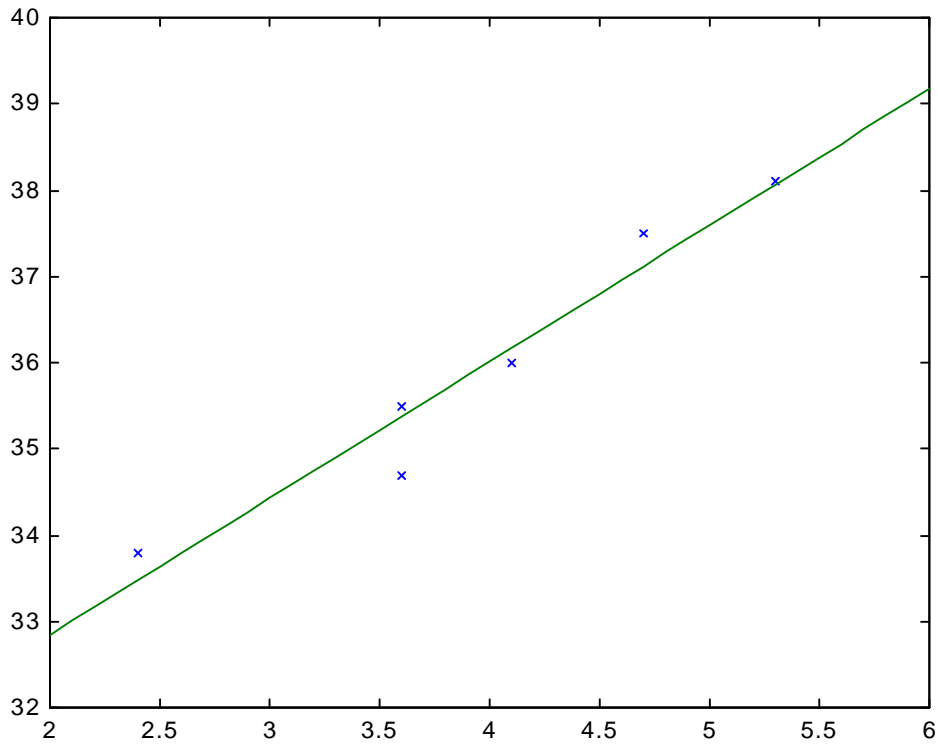
Synopsis (as used):

`plot(X1,Y1,'linetype1',X2,Y2,'linetype2',...)`

`plot(X,Y)` plots vector `X` versus vector `Y`. If `X` or `Y` is a matrix, then the vector is plotted versus the rows or columns of the matrix, whichever line up.

Various line types, plot symbols and colors can be obtained with `plot(X,Y,'linetype')` where `linetype` is a 1-, 2-, or 3-character string made from the following characters:

.	point	y	yellow
o	circle	m	magenta
x	x-mark	c	cyan
+	plus	r	red
*	star	g	green
-	solid line	b	blue
:	dotted line	w	white
-.	dashdot line	k	black
-	dashed line		



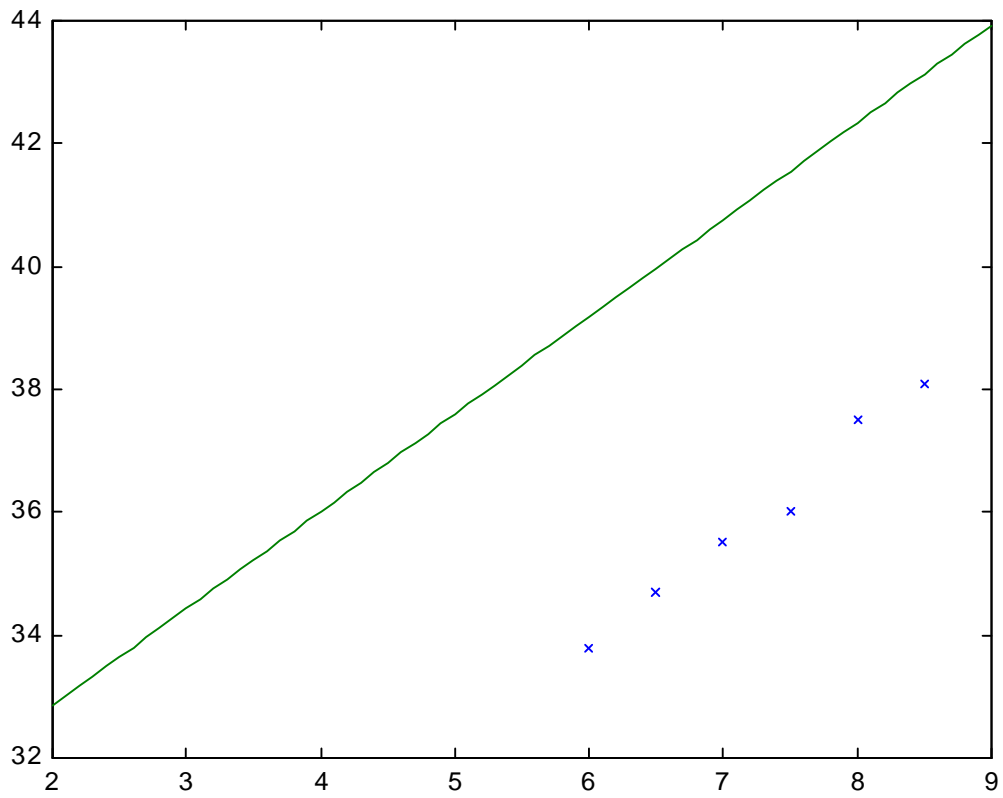
Matlab Input:

```
a = [2.4 3.6 3.6 4.1 4.7 5.3]'  
x = [6.0 6.5 7.0 7.5 8.0 8.5]'  
y = [33.8 34.7 35.5 36.0 37.5 38.1]'  
A = [a, ones(size(x))]  
c = A\y  
t = 2:0.1:9;  
z = polyval(c,t);  
plot(x,y,'x',t,z)
```

Matlab Output:

```
a =  
    2.4000    3.6000    3.6000    4.1000    4.7000    5.3000  
x =  
    6.0000    6.5000    7.0000    7.5000    8.0000    8.5000  
y =  
    33.8000  
A =  
    2.4000    1.0000  
    3.6000    1.0000  
    3.6000    1.0000  
    4.1000    1.0000  
    4.7000    1.0000  
    5.3000    1.0000  
c =  
    1.5826  
   29.6821
```

Thomas Penick 452 80 6040
M 340L-C March 12, 1998



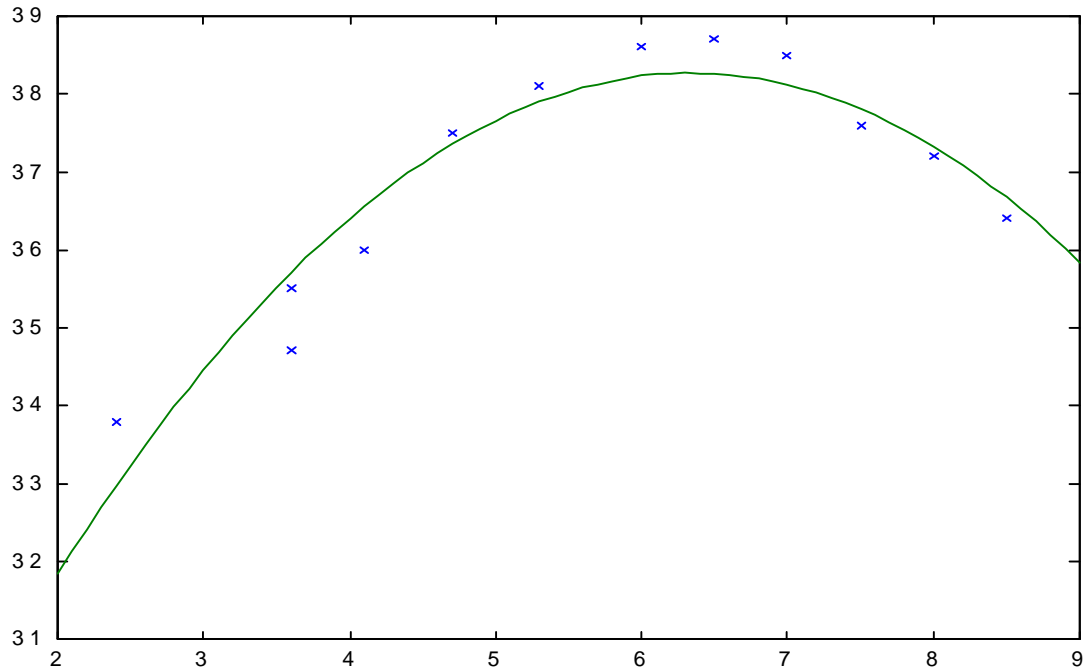
Chapter 6, section 1, problem 5: Computing a Least-Squares Polynomial

Matlab Input:

```
x = [2.4 3.6 3.6 4.1 4.7 5.3 6.0 6.5 7.0 7.5 8.0 8.5]'  
y = [33.8 34.7 35.5 36.0 37.5 38.1 38.6 38.7 38.5 37.6 37.2 36.4]'  
plot(x,y,'x')  
A = [x.^2, x, ones(size(x))]  
c = A\y  
t = 2:0.1:9;  
z = polyval(c,t);  
plot(x,y,'x',t,z)  
p = polyder(c)  
peak = roots(p)
```

Matlab Output:

```
x =  
    2.4000  
    3.6000  
    3.6000  
    4.1000  
    4.7000  
    5.3000  
    6.0000  
    6.5000  
    7.0000  
    7.5000  
    8.0000  
    8.5000  
y =  
    33.8000  
    34.7000  
    35.5000  
    36.0000  
    37.5000  
    38.1000  
    38.6000  
    38.7000  
    38.5000  
    37.6000  
    37.2000  
    36.4000  
A =  
    5.7600    2.4000    1.0000  
   12.9600    3.6000    1.0000  
   12.9600    3.6000    1.0000  
   16.8100    4.1000    1.0000  
   22.0900    4.7000    1.0000  
   28.0900    5.3000    1.0000  
   36.0000    6.0000    1.0000  
   42.2500    6.5000    1.0000  
   49.0000    7.0000    1.0000  
   56.2500    7.5000    1.0000  
   64.0000    8.0000    1.0000  
   72.2500    8.5000    1.0000  
c =  
   -0.3420  
    4.3353  
   24.5317  
p =  
   -0.6840    4.3353  
peak =  
    6.3376
```



ABOUT THE MATLAB COMMANDS

roots Polynomial roots.

Synopsis: `r = roots(p)`

Polynomial coefficients are ordered in descending powers. If `c` is a row vector containing the coefficients of a polynomial, `roots(c)` is a column vector whose elements are the roots of the polynomial.

If `r` is a column vector containing the roots of a polynomial, `poly(r)` returns a row vector whose elements are the coefficients of the polynomial.

polyder Polynomial derivative.

Synopsis:

`k = polyder(p)`

`k = polyder(a,b)`

`[q,d] = polyder(b,a)`

`k = polyder(p)`, where `p` is a vector whose elements are the coefficients of a polynomial in descending powers, returns the derivative of that polynomial. `k` is a vector containing the coefficients of the derivative in descending powers.

`k = polyder(a,b)` returns the derivative of the product of the polynomials `a` and `b`.

`[q,d] = polyder(b,a)` returns the derivative of the polynomial quotient `b/a`, where the derivative is represented by `q/d`.