

CHAPTER 13

Vectors and Curves in the Plane

A vector whose initial point is at the origin is said to be in **standard position**. A variable which represents a vector may be written \vec{v} or \mathbf{v} .

Definition of Component Form of a Vector in the Plane:

13.1 p728 If \vec{v} is a vector in the plane whose initial point is the origin and whose terminal point is (v_1, v_2) , then the component form of \vec{v} is given by

$$\vec{v} = \langle v_1, v_2 \rangle$$

The coordinates v_1 and v_2 are called the **components of \vec{v}** . If both the initial point and the terminal point lie at the origin, then \vec{v} is called the **zero vector** and is denoted by

$$\mathbf{0} = \langle 0, 0 \rangle$$

To convert Directed Line Segments to Component form

or vice versa, we use the following procedures. 13.1 p728

- If $P = (p_1, p_2)$ and $Q = (q_1, q_2)$, then the component form of the vector \vec{PQ} represented by $P\vec{Q}$ is $\langle v_1, v_2 \rangle = \langle q_1 - p_1, q_2 - p_2 \rangle$. Moreover, the **magnitude or norm** (length) of \vec{v} is given by

$$\|\vec{v}\| = \sqrt{(q_1 - p_1)^2 + (q_2 - p_2)^2} = \sqrt{v_1^2 + v_2^2} \quad \text{length of a vector}$$

The length of \vec{v} is also called the **norm of \vec{v}** . If $\|\vec{v}\| = 1$, then \vec{v} is called a **unit vector**.

- If $\vec{v} = \langle v_1, v_2 \rangle$, then \vec{v} can be represented by the directed line segment, in standard position, from $P = (0, 0)$ to $Q = (v_1, v_2)$.

Standard Unit Vectors: 13.1 p733

$$\vec{i} = \langle 1, 0 \rangle \quad \vec{j} = \langle 0, 1 \rangle$$

We call $\vec{v} = v_1\vec{i} + v_2\vec{j}$ a **linear combination** of \vec{i} and \vec{j} .

The scalars v_1 and v_2 are called the **horizontal and vertical components of \vec{v}** , respectively. In other words, the vector $\langle 2, 3 \rangle$ expressed in **component form** would be $2\vec{i} + 3\vec{j}$.

Definition of Vector Addition and Scalar Multiplication:

13.1 p730 For vectors $\vec{u} = \langle u_1, u_2 \rangle$ and $\vec{v} = \langle v_1, v_2 \rangle$ and scalar k , we define the following operations.

- The **vector sum** of \vec{u} and \vec{v} is the vector $\vec{u} + \vec{v} = \langle u_1 + v_1, u_2 + v_2 \rangle$
- The **scalar multiple** of k and \vec{u} is the vector $k\vec{u} = \langle ku_1, ku_2 \rangle$.

- The **negative** of \vec{v} is the vector $-\vec{v} = (-1)\vec{v} = \langle -v_1, -v_2 \rangle$.

- The **difference** of \vec{u} and \vec{v} is $\vec{u} - \vec{v} = \vec{u} + (-\vec{v}) = \langle u_1 - v_1, u_2 - v_2 \rangle$

Properties of Vector Addition and Scalar Multiplication:

13.1 p731 Let \vec{u} , \vec{v} , and \vec{w} be vectors in the plane, and let c and d be scalars.

- $\vec{u} + \vec{v} = \vec{v} + \vec{u}$ commutative property
- $(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$ associative property
- $\vec{u} + \mathbf{0} = \vec{u}$
- $\vec{u} + (-\vec{u}) = \mathbf{0}$
- $c(d\vec{u}) = (cd)\vec{u}$
- $(c + d)\vec{u} = c\vec{u} + d\vec{u}$
- $c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$ distributive property
- $1(\vec{u}) = \vec{u}$, $0(\vec{u}) = \mathbf{0}$ distributive property

Length of a Scalar Multiple: 13.1 p731 Let \vec{v} be a vector and c be a scalar. Then

$$\|c\vec{v}\| = |c| \|\vec{v}\| \quad \text{where } |c| \text{ is the absolute value of } c.$$

Unit vector in the direction of \vec{v} : 13.1 p732 If \vec{v} is a nonzero vector in the plane, then the vector

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = \frac{l}{\|\vec{v}\|} \vec{v}$$

has length l and the same direction as \vec{v} .

Triangle Inequality: 13.1 p733 If \vec{u} and \vec{v} are vectors in the plane, then

$$\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|.$$

Determining a Vector as a function of an angle: 13.1 p734 If \vec{v} is a **unit vector** with angle θ with respect to the positive x -axis, then $\vec{u} = \langle \cos\theta, \sin\theta \rangle = \cos\theta\vec{i} + \sin\theta\vec{j}$

$$2) W = \vec{F} \cdot \vec{PQ}$$

Dot product form

Dot Product: 13.2 p738 The **dot product** of $\vec{u} = \langle u_1, u_2 \rangle$ and $\vec{v} = \langle v_1, v_2 \rangle$ is $\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2$. The dot product is a product of vector values; the i and j are dropped from the result.

Properties of the Dot Product: 13.2 p738 If \vec{u} , \vec{v} , and \vec{w} are vectors in the plane and c is a scalar, then the following properties are true.

1. $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$ commutative property
2. $\vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$ distributive property
3. $c(\vec{u} \cdot \vec{v}) = (c\vec{u}) \cdot \vec{v} = \vec{u} \cdot (c\vec{v})$
4. $0 \cdot \vec{v} = 0$
5. $\vec{v} \cdot \vec{v} = \|\vec{v}\|^2$

Angle between two vectors: 13.2 p739 If θ is the angle between two nonzero vectors \vec{u} and \vec{v} , then

$$\cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \quad \text{and} \quad \vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

Definition of Orthogonal Vectors: 13.2 p740 The vectors \vec{u} and \vec{v} are **orthogonal** if $\vec{u} \cdot \vec{v} = 0$. We consider the zero vector to be orthogonal to every vector \vec{u} since $0 \cdot \vec{u} = 0$.

Two nonzero vectors are **parallel** if they have the same or opposite directions.

Projection and Vector Components: 13.2 p742 Let \vec{u} and \vec{v} be nonzero vectors with $\vec{u} = \vec{w}_1 + \vec{w}_2$, where \vec{w}_1 is parallel to \vec{v} and \vec{w}_2 is orthogonal to \vec{v} .

\vec{w}_1 is the **projection of \vec{u} onto \vec{v}** or the vector component of \vec{u} along \vec{v} , and is denoted by $\vec{w}_1 = \text{proj}_{\vec{v}} \vec{u}$.

$\vec{w}_2 = \vec{u} - \vec{w}_1$ and is called the **vector component of \vec{u} orthogonal to \vec{v}** .

We can find the vector component \vec{w}_2 once we have found the projection of \vec{u} onto \vec{v} .

Finding Projection: 13.2 p742

$$\text{proj}_{\vec{v}} \vec{u} = \left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{v}\|^2} \right) \vec{v}$$

Definition of Work: 13.2 p744 The work W done by a constant force \vec{F} as its point of application moves along the vector \vec{PQ} is given by either of the following:

$$1) W = \left\| \text{proj}_{\vec{PQ}} \vec{F} \right\| \left\| \vec{PQ} \right\| \quad \text{Projection form}$$

Vector-Valued Function: 13.3 p746 A function of the form:

$$\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j}$$

is called a **vector-valued function**, where the component functions, f and g , are real-valued functions of the parameter t .

The **domain** of the vector-valued function \vec{r} is the intersection of the domains of f and g .

The **limit** of the vector-valued function \vec{r} is

$$\lim_{t \rightarrow a} \vec{r}(t) = \left[\lim_{t \rightarrow a} f(t) \right] \vec{i} + \left[\lim_{t \rightarrow a} g(t) \right] \vec{j}$$

provided that f and g have limits as $t \rightarrow a$.

The vector-valued function \vec{r} is **continuous** at the point given by $t = a$ if the limit exists as $t \rightarrow a$ and

$$\lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$$

A vector-valued function is **continuous** on an interval if it is continuous at every point in the interval.

The vector-valued function $\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j}$ is **smooth** on an open interval I if f' and g' are continuous on I and $\vec{r}'(t) \neq 0$ for any value of t in the interval I .

The Derivative of a Vector-Valued Function: 13.3 p750

$$\vec{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}$$

for all t for which the limit exists.

Differentiation of Vector-Valued Functions: 13.3 p750 If

$\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j}$ where f and g are differentiable functions of t , then $\vec{r}'(t) = f'(t)\vec{i} + g'(t)\vec{j}$.

Properties of the derivative of Vector-Valued Functions: 13.3 p752

- 1) $D_t[c\vec{r}(t)] = c\vec{r}'(t)$
- 2) $D_t[\vec{r}(t) \pm \vec{u}(t)] = \vec{r}'(t) \pm \vec{u}'(t)$
- 3) $D_t[f(t)\vec{r}(t)] = f(t)\vec{r}'(t) + f'(t)\vec{r}(t)$
- 4) $D_t[\vec{r}(t) \cdot \vec{u}(t)] = \vec{r}(t) \cdot \vec{u}'(t) + \vec{r}'(t) \cdot \vec{u}(t)$
- 5) $D_t[\vec{r}(f(t))] = \vec{r}'(f(t))f'(t)$
- 6) If $\vec{r}(t) \cdot \vec{r}(t) = c$, then $\vec{r}(t) \cdot \vec{r}'(t) = 0$.

Integration of a Vector-Valued Function: 13.3 p753 If

$\vec{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j}$ where f and g are continuous on $[a, b]$, then the **indefinite integral** of \vec{r} is

$$\int \vec{r}(t) dt = \left[\int f(t) dt \right] \mathbf{i} + \left[\int g(t) dt \right] \mathbf{j}$$

and its **definite integral** over the interval $a \leq t \leq b$ is

$$\int_a^b \vec{r}(t) dt = \left[\int_a^b f(t) dt \right] \mathbf{i} + \left[\int_a^b g(t) dt \right] \mathbf{j}$$

Velocity and Acceleration: 13.4 p757 For the function

$$\vec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j},$$

$$\text{velocity} = \vec{v}(t) = \vec{r}'(t) = x'(t)\mathbf{i} + y'(t)\mathbf{j}$$

$$\text{acceleration} = \vec{a}(t) = \vec{r}''(t) = x''(t)\mathbf{i} + y''(t)\mathbf{j} = a_T \vec{T}(t) + a_N \vec{N}(t)$$

$$\text{speed} = \|\vec{v}(t)\| = \|\vec{r}'(t)\| = \sqrt{[x'(t)]^2 + [y'(t)]^2} = \frac{ds}{dt}$$

Circular Function: 13.4 p758 The rectangular equation for a circle is $x^2 + y^2 = r^2$. The vector-valued function for a circular path of counterclockwise motion is:

$$\vec{c}(t) = r \cos \frac{[\text{spd}]t}{r} \mathbf{i} + r \sin \frac{[\text{spd}]t}{r} \mathbf{j}$$

where r = radius

t = time

[spd] = speed

When the motion is at a constant speed, the velocity vector is tangent to the circle and the acceleration vector is directed toward the center.

Gravitational Constant: 13.4 p760 $g = 32 \text{ ft./sec./sec.}$

$$g = 9.81 \text{ meters/sec./sec.}$$

Position Function for a Projectile: 13.4 p761 The path of

a projectile launched from an initial height h with initial speed v_0 and angle of elevation θ is described by the vector function

$$\vec{r}(t) = (v_0 \cos \theta)t \mathbf{i} + \left[h + (v_0 \sin \theta)t - \frac{1}{2}gt^2 \right] \mathbf{j}$$

Unit Tangent Vector: 13.5 p764 Let C be a smooth curve

represented by \vec{r} on an open interval I . If $\vec{r}'(t) \neq 0$,

then the unit tangent vector $\vec{T}(t)$ at t is defined to be

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$$

Normal means perpendicular.

Principal Unit Normal Vector: 13.5 p765 Let C be a

smooth curve represented by \vec{r} on an open interval I .

If $\vec{T}'(t) \neq 0$, then the principal unit normal vector at t

is defined to be

$$\vec{N}(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}$$

The **normal vector** $\vec{N}(t)$ can be difficult to calculate but if $\vec{T}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$, and there is zero acceleration, then $\vec{N}(t)$ is either

$$y(t)\mathbf{i} - x(t)\mathbf{j} \quad [\text{clockwise curve}]$$

or $-y(t)\mathbf{i} + x(t)\mathbf{j}$ [counterclockwise curve]

The correct choice is the vector pointing to the inside of the curve of $\vec{r}(t)$. In other words, $\vec{N}(t)$ is at a right angle to $\vec{T}(t)$ which yields the two possibilities.

Tangential and Normal Components of Acceleration:

13.5 p768 Let $\vec{r}(t)$ be the position vector for a smooth curve C , and let the acceleration vector be represented by

$$\vec{a}(t) = a_T \vec{T} + a_N \vec{N} = (\vec{a} \cdot \vec{T})\vec{T} + (\vec{a} \cdot \vec{N})\vec{N}$$

We call $a_T = \vec{a} \cdot \vec{T} = \frac{d^2s}{dt^2}$ the **tangential component**

of acceleration, and we call $a_N = \vec{a} \cdot \vec{N} = K \left(\frac{ds}{dt} \right)^2$

the **normal component of acceleration**.

Note that calculations for a_T and a_N involve points rather than functions so that the \mathbf{i} and \mathbf{j} do not appear in the result. Or at least I think that's what's going on.

Arc Length of a Plane Curve: 13.6 p772 If C is a smooth

curve given by $\vec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ on an interval $[a, b]$,

then the arc length of C on the interval is

$$s = \int_a^b \|\vec{r}'(t)\| dt$$

Arc Length Function: 13.6 p722 Let C be a smooth curve

given by $\vec{r}(t)$ defined on the closed interval $[a, b]$.

For $a \leq t \leq b$, the **arc length function** is given by

$$s(t) = \int_a^t \|\vec{r}'(\tau)\| d\tau$$

t is the lowercase Greek letter tau.

Derivative of the Arc Length Function: 13.6 p773 Let C be a smooth curve given by $\vec{r}(t)$ defined on the closed interval $[a, b]$. The derivative of the arc length function s for this curve is given by

$$\frac{ds}{dt} = \|\vec{r}'(t)\|$$

In differential form, we can write $ds = \|\vec{r}'(t)\|dt$.

Arc Length Parameter: 13.6 p774 If C is a smooth curve given by $\vec{r}(s) = x(s)\mathbf{i} + y(s)\mathbf{j}$, where s is the arc length parameter, then

$$\|\vec{r}'(s)\| = 1$$

Moreover, if t is any parameter for the vector-valued function \vec{r} such that $\|\vec{r}'(t)\| = 1$, then t must be the **arc length parameter**.

Curvature: 13.6 p774 Let C be a smooth curve given by $\vec{r}(s)$, where s is the **arc length parameter**. The curvature at s is given by

$$K = \left\| \frac{d\vec{T}}{ds} \right\| = \|\vec{T}'(s)\| = \|\vec{r}''(s)\|$$

If C is a smooth curve given by $\vec{r}(t)$, then the curvature of C at t is given by

$$K = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|}$$

If C is a curve with curvature K at point P , a circle passing through the point P with radius $r = 1/K$ is called the **circle of curvature** if the circle lies on the concave side of the curve and shares a common tangent line with the curve at the point P . We call r the **radius of curvature** at P , and the center of the circle is called the **center of curvature**.

In rectangular coordinates, if C is the graph of a twice differentiable function given by $y = f(x)$, then the curvature at the point (x, y) is given by

$$K = \frac{|y''|}{[1 + (y')^2]^{3/2}}$$

For a function given by $x = x(t)$, $y = y(t)$, then the curvature at the point (x, y) is given by

$$K = \frac{|x'y'' - y'x''|}{[(x')^2 + (y')^2]^{3/2}}$$

Acceleration, Speed, and Curvature: 13.6 p778 If $\vec{r}(t)$ is the position vector for a smooth curve C , then the acceleration vector is given by

$$\vec{a}(t) = \frac{d^2s}{dt^2}\vec{T} + K\left(\frac{ds}{dt}\right)^2\vec{N}$$

where K is the curvature of C and ds/dt is the speed.

Force: 13.6 p778

$$\vec{F} = m\vec{a} = m\left(\frac{d^2s}{dt^2}\right)\vec{T} + mK\left(\frac{ds}{dt}\right)^2\vec{N}$$

m = mass

K = curvature