## TIME-DOMAIN ANALYSIS OF A CONTINUOUS-TIME SYSTEM

An Example using The Classical Method

## THE PROBLEM

Solve the system equation:	$(D^{2} + 3D + 2)y(t) = Df(t)$
If the input is:	$f(t) = t^2 + 5t + 3$
And the initial conditions are:	y(0) = 2 and $Dy(0) = 3$

This problem is also solved using the **frequency-domain method** (Laplace transform); see the document **LaplaceExample.pdf**.

## THE SOLUTION

The characteristic polynomial of the system is	s $\lambda^2 + 3\lambda + 2 = (\lambda + 1)(\lambda + 2) = 0$	
The roots of the system are	$\lambda = -1, -2$	
The characteristic modes of the system are	$e^{-t}, e^{-2t}$	
The natural response of the system is then: The arbitrary constants $a_1$ and $a_2$ will be determined later by the initial conditions.	$y_n(t) = a_1 e^{-t} + a_2 e^{-2t}$	(Eq 4)
The forced response to the input $t^2 + 5t + 3$	is $y_f(t) = b_2 t^2 + b_1 t + b_0$	(Eq 5)
$y_f(t)$ satisfies the system equation	$(D^2 + 3D + 2)y_f(t) = Df(t)$	(Eq 6)
$Dy_f(t)$ and $D^2y_f(t)$ are found from (Eq 5)	$Dy_{f}(t) = \frac{d}{dt}(b_{2}t^{2} + b_{1}t + b_{0}) = 2b_{2}t + b_{1}$ $D^{2}y_{f}(t) = \frac{d}{dt}(2b_{2}t + b_{1}) = 2b_{2}$	(Eq 7) (Eq 8)
The derivative of the input $f(t)$ is found	$Df(t) = \frac{d}{dt}(t^2 + 5t + 3) = 2t + 5$	
Taking equation (Eq 6):	$(D^{2} + 3D + 2)y_{f}(t) = Df(t)$	
Rewriting (Eq 6):	$D^{2}y_{f}(t) + 3Dy_{f}(t) + 2y_{f}(t) = Df(t)$	
And substituting (Eq 8), (Eq 7), (Eq 5):	$2b_2 + 3(2b_2t + b_1) + 2(b_2t^2 + b_1t + b_0) = 2t + b_1t + b_0 = 2t + b_1t + b_1t + b_0 = 2t + b_1t + b_$	5
And regrouping to powers of <i>t</i> :	$2b_2t^2 + (2b_1 + 6b_2)t + (2b_0 + 3b_1 + 2b_2) = 2t$	+5

Equating coefficients of similar powers on both sides of the expression:

$$2b_2 = 0 \\ 2b_1 + 6b_2 = 2 \\ 2b_0 + 3b_1 + 2b_2 = 5$$

Solving these three equations we get:

Therefore, from (Eq 5):

We have:

The total system response is the sum of the natural and the forced solutions:

So from (Eq 4) and (Eq 19) we have:

And, taking the derivative:

So with the initial conditions: Substituting into (Eq 21): Substituting into (Eq 22):

$$b_0 = 1, \ b_1 = 1, \ b_2 = 0$$
  
$$y_f(t) = b_2 t^2 + b_1 t + b_0$$
  
$$y_f(t) = t + 1, \ t > 0$$
 (Eq 19)

$$y(t) = y_n(t) + y_f(t)$$
  

$$y(t) = (a_1 e^{-t} + a_2 e^{-2t}) + (t+1)$$
 (Eq 21)  

$$Dy(t) = -a_1 e^{-t} - 2a_2 e^{-2t} + 1$$
 (Eq 22)

$$Dy(t) = -a_1 e^{-t} - 2a_2 e^{-t} + 1)$$
 (Eq 22)

$$y(0) = 2$$
 and  $Dy(0) = 3$   
 $2 = a_1 + a_2 + 1$   
 $3 = -a_1 - 2a_2 + 1$ 

 $a_1 = 4, a_2 = -3$ 

Solving these two equations we get:

## THE ANSWER

Therefore, from (Eq 21):	$y(t) = (a_1 e^{-t} + a_2 e^{-2t}) + (t+1)$
We have:	$y(t) = 4e^{-t} - 3e^{-2t} + t + 1,  t > 0$